Amendments to the claims:

1. (currently amended) A rotary hammer, comprising:

a main body;

an impact mechanism integrated into the main body, wherein said impact mechanism generates axial impact impulses on a tool in a working direction;

a handle that is movably supported relative to the main body; and

a vibration-shielding unit connecting the handle with the main body and having a return element that produces a spring force,

wherein the vibration-shielding unit comprises a guide device (12) for guiding a motion of the handle along a straight line in the working direction such that the handle is movable in the working direction against the spring force;

wherein the guide device comprises two force-transmission elements which are interconnected by a connecting element and are configured to perform a scissors-type motion pivotal connection in a central region of at least one of the force-transmission elements;

wherein the return element is arranged perpendicular to the working direction; is directly contacted with a surface of each of the force-transmission elements and connects said force-transmission elements with each other; and is located in the working direction in a region between the connecting element and the handle; ~~and engages with each of the force-transmission elements on a side of each force-transmission element that faces the handle;~~ and

wherein each of the force-transmission elements is supported on at least one end such that it is displaceable in a direction extending perpendicular to a direction of motion.

2. (previously presented) The rotary hammer as recited in Claim 1, wherein the handle is positioned at a distance away from the main body.

3. (canceled)

4. (canceled)

5. (previously presented) The rotary hammer as recited in Claim 1, wherein the connecting element (24) is located in a central region of at least one of the force-transmission elements (20, 22).

6. (canceled)

7. (canceled)

8. (canceled)

9. (previously presented) The rotary hammer as recited in Claim 1, characterized by at least one elastically deformable impact-absorption element (32).

10. (previously presented) The rotary hammer as recited in Claim 1, wherein the return element is configured as an elastically deformable impact-absorption element.

11. (previously presented) The rotary hammer as recited in Claim 1, wherein the return element (30) engages with at least one force-transmission element (20, 22).

12. (canceled)

13. (previously presented) The rotary hammer as recited in claim 1, wherein at least a part of a first force-transmission element (20, 22) extends in a longitudinal direction of said first force-transmission element (20, 22) over a cross-over point of said force-transmission elements (20, 22) based on a cross-over point of said force-transmission elements (20, 22), wherein said part of said first force-transmission element (20, 22) has a length which is longer than a width of one of said force-transmission elements (20, 22), wherein said width is an extension of one of said force-transmission elements (20, 22) which is perpendicular in respect to the length in the longitudinal direction of the same force-transmission element (20, 22).

14. (previously presented) The rotary hammer as recited in claim 1, wherein one force-transmission element (20, 22) divides the other force-transmission element (20, 22) into equal halves.

15. (previously presented) The rotary hammer as recited in claim 1, wherein the two force-transmission elements (20, 22) have a shape of an X.

16. (previously presented) The rotary hammer as recited in claim 2, wherein the distance has a value between 1 cm and 1.5 cm.

17. (canceled)

18. (previously presented) The rotary hammer as recited in claim 5, wherein a central region divides the force-transmission elements (20, 22) into equal halves.

19. (canceled)

20. (previously presented) The rotary hammer as recited in claim 1, wherein each of the force-transmission elements (20, 22) extends from a first bolt (44, 46) via a connecting element (24) to a second bolt (48, 50) which is arranged opposite to the first bolt (44, 46).

21. (previously presented) The rotary hammer as recited in claim 20, wherein each of the force-transmission elements (20, 22) is displaceably supported in a second bolt (48, 50), wherein said second bolt (48, 50) is engaged in a slot (54, 56).

22. (previously presented)The rotary hammer as recited in claim 21, wherein a limitation of a movement of a force-transmission element (20, 22) is mediated by an end (58, 60, 62, 64) of the slot (54, 56).

23. (previously presented) The rotary hammer as recited in claim 20, wherein one bolt (44, 48) of each force-transmission element (20, 22) is arranged at the handle and the other bolt (46, 50) of each force-transmission element (20, 22) is arranged at the main body.

24. (previously presented) The rotary hammer as recited in claim 21, wherein one slot (54) is arranged at the handle and the other slot (56) is arranged at the main body.

25. (currently amended) A rotary hammer, comprising:

a main body;

an impact mechanism integrated into the main body, wherein said impact mechanism generates axial impact impulses on a tool in a working direction;

a handle that is movably supported relative to the main body; and

a vibration-shielding unit connecting the handle with the main body and having a return element that produces a spring force;

wherein the vibration-shielding unit comprises a guide device for guiding a motion of the handle along a straight line in the working direction such that the handle is movable in the working direction against the spring force;

wherein the guide device comprises two force-transmission elements which are interconnected by a connecting element in a central region of at least one of the force-transmission elements and are configured to perform a scissors-type motion;

wherein the return element is arranged perpendicular to the working direction; is directly contacted with a surface of each of the force-transmission elements and connects said force-transmission elements with each other; and is located in the working direction in a region between the connecting element and the handle; ~~and engages with each of the force-transmission elements on a side of each force-transmission element that faces the handle;~~

wherein the force-transmission elements are pivotably supported via first bolts on at least a first end of each force-transmission element;

wherein one of the force-transmission elements is pivotably supported on the main body via one of the first bolts and the other force-transmission element is pivotably supported on the handle via one of the first bolts;

wherein the force-transmission elements are supported on a second end of each force-transmission element via second bolts such that each second end of the force-transmission elements is displaceable in a direction extending perpendicular to the direction of motion;

wherein the first end of each force-transmission element is located opposite to the second end of each force-transmission element;

wherein said second bolts are displaceably engaged in slots; and

wherein one of the slots is arranged at the handle and the other slot is arranged at the main body.

26. (canceled)

27. (currently amended) A rotary hammer, comprising:

a main body;

an impact mechanism integrated into the main body, wherein said impact mechanism generates axial impact impulses on a tool in a working direction;

a handle that is movably supported relative to the main body; and

a vibration-shielding unit connecting the handle with the main body and having a return element that produces a spring force,

wherein the vibration-shielding unit comprises a guide device ~~(12)~~ for guiding a motion of the handle along a straight line in the working direction such that the handle is movable in the working direction against the spring force; ~~and~~

wherein the guide device comprises two force-transmission elements which are interconnected by a connecting element and are configured to perform a scissors-type motion pivotal connection in a central region of at leas tone of the force-transmission elements;;

wherein the force-transmission elements intersect one another in said central region and are connected with one another by said connecting element in said central region;

wherein each of the force-transmission elements have two opposite ends, and the force-transmission elements are arranged so that one of the opposite ends of the two force-transmission elements is connected with the handle and the other of the two opposite ends of the two force-transmission elements is connected to the main body;

wherein the return element is arranged perpendicular to the working direction; is directly contacted with a surface of each of the force-transmission elements and connects said force-transmission elements with each other; and is located in the working direction in a region between the connecting element and the handle; ~~and engages with each of the force-transmission elements on one of the two opposite ends of each force-transmission element that faces the handle;~~ and

wherein each of the force-transmission elements is supported on at least one end such that it is displaceable in a direction extending perpendicular to a direction of motion.